# Automated Computer Vision Inspection System for Conveyance amazon

Team #5

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### Background

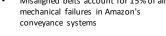
Amazon houses on average 11-22 miles of conveyance belts per fulfillment center, the belt failure increases downtime and costs millions of dollars.

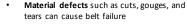


Belt Tracking

- A belt rip occurs when the belt separates or tears apart, causing a complete belt failure
- Package damage or other abrasions can cause rips and tears in the belt
- Splices are staples joining a belt together, which are susceptible to damage and can become weak points that may result in a rip

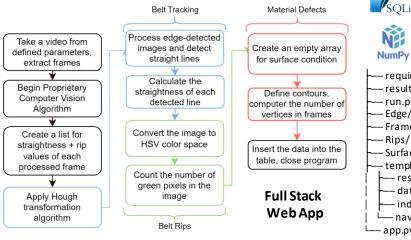


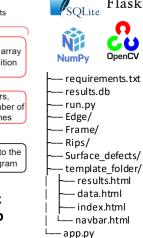




# Hardware & Software







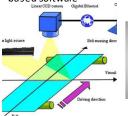
# Scope of Work

- Detects rips, material defects, alignment
- Affordable (BOM <= \$400)
- Recommend maintenance from KPIs



#### **Existing Solutions**

Existing solutions for conveyor belt failure mode detection at Amazon sort centers mainly rely on regular walkthrough inspections by maintenance personnel. Other systems at Amazon, such as sensors that detect changes in temperature, vibration, or motor current, do not monitor belt health or generate a predictive maintenance report utilizing visionbased software





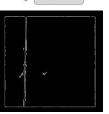
# **Testing**

Camera Vision	Pros	Cons
ELP 2.0 MP USB Camera	<ul> <li>120fps</li> </ul>	<ul> <li>Only 720P at</li> </ul>
	<ul> <li>Inexpensive: \$60&gt;</li> </ul>	120fps
	<ul> <li>Wide Angle Lens</li> </ul>	
	<ul> <li>Ease to Use</li> </ul>	
	<ul> <li>Compact</li> </ul>	
NVIDIA Jetson Nano	<ul> <li>High Processing Power</li> </ul>	<ul> <li>Can be difficult to</li> </ul>
	<ul> <li>Many different ports</li> </ul>	use
	<ul> <li>Small Footprint</li> </ul>	<ul> <li>Expensive</li> </ul>
Raspberry Pi 3B+	<ul> <li>Small Footprint</li> </ul>	<ul> <li>Very Slow</li> </ul>
	<ul> <li>Inexpensive</li> </ul>	
Logitech Desktop External	<ul> <li>Inexpensive</li> </ul>	<ul> <li>Requires a PC</li> </ul>
Camera	<ul> <li>Easy to use</li> </ul>	<ul> <li>Low frame rate</li> </ul>
		and low resolution
Kinect 360 Camera	Free	<ul> <li>Bulky</li> </ul>
		<ul> <li>Low resolution</li> </ul>
High Speed Camera	<ul> <li>Best framerate</li> </ul>	<ul> <li>Extremely</li> </ul>
Attachment	<ul> <li>Best Resolution</li> </ul>	Expensive
	<ul> <li>Compact</li> </ul>	







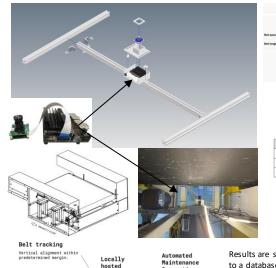


Surface Condition

Material (amnesty), belt surface condition

Belt Rips

### **Final Design**



website

Inspections



Average straightness value  Total number of rips  Average overall surface condition			9.738206374955682 0 31.78181818181818 vertices			80-100		Bad		
						les	Good			
						500-1000 vertices		Bad		
	ID Average Straight		ness Blue Values		Average Number of Vertices		Average Solidity		Date	Time
	1	35.20061111111	111	loi .	36.5		0.1665847722144	12078	2023- 03-05	17:19:0
2 0.0			10, 0, 0, 0, 0, 0, 0, 0, 0	0.0		0.0		2023- 04-06	16:52:5	
7 7	, 2	0.0		0,	0.0		0.0		2023- 04-06	16:52:5

1900	ID	Average Straightness	Blue Values	Average Number of Vertices	Average Solidity	Date	Time
	1	35.20061111111111	lol	36.5	0.16658477221442078	2023- 03-05	17:19:00
	2	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-06	16:52:52
	3	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-08	13:04:23
	4	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-08	13:12:32
Results are saved to a database after auto and manual	5	0.0	(0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,0,	0.0	0.0	2023- 04-08	13:13:08
	6	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-08	13:13:18
run. Able to store	7	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-08	13:19:14
5+ year of data	٠	0.0	[0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0, 0	0.0	0.0	2023- 04-08	13:33:28