

Model Based System Engineering

Team #29 Members: Maximilian Salazar, Sidney Goodman, Kabrea Rostochak, Jocelyn Moranchel Mentors: Ralph Munguia & Nathan Rimkus



EST. 1943 -

Customer Background

Los Alamos National Laboratory (LANL)
Federally Funded Research
& Development Center. They perform
work for the Department of Defense
(DoD), Intelligence Community (IC), and
Department of Homeland Security
(DHS), among others.

Problem Statement / Scope of Work

Create a model-based system Model DeWalt Electric Mower

Focus:

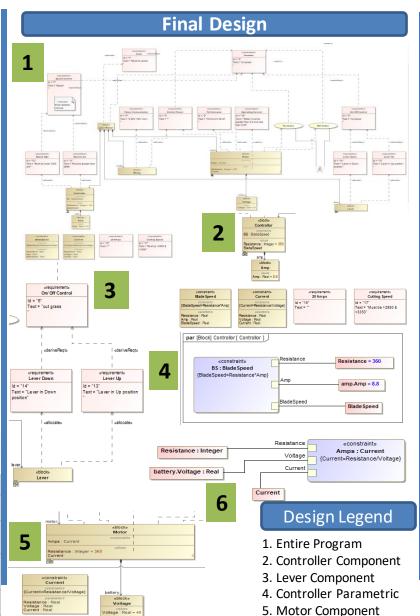
- How to use the Cameo
- Research on the mower
- Create the models in Cameo
- Test the model with constraints & satisfy functions

Requirements

FMEA

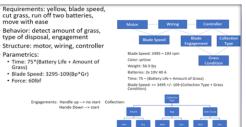
- Repeatable & Adaptable
- Reduce Design Time
- Four Pillars of MBSE

	System Subsystem	Purdue				FALUS	EM	POTENTIAL COE AND EFFE (DESIGN FME													
Zem				T	é		Ī.	100000	0.00		Ť		à	72	A	ction Res	uts				
Function	Requirements	Potential Failure Mode	Potential Effect(s) of Failure	Severity	Classification	Potential Causes(s) of Failure	Occurrence	Current Design Controls Prevention	Ourient Design Controls Detection	Detection	RPN	Recommend ed Action(s)	Responsibilit	Target Completion Date	Actions Taken	Effective Date	Severity	Occurrence	Detection		Impro ve %
1	Affordability Less than \$1000	If bill of material goes over \$1000 it would not meet the project requirments	Will affect student budget	8	4	Cost of magic draw software may go over budget \$1000	1	Using carried student version Budget limit	Budget limit	10	1	action required	josely n	10/15/2021	Buy budget triendly		8	1	1		0.0%
2	Digital assembly (carreo) Customer wants model to be able to show how using MBSE can aid.	ACCESS to magic draw or cameo could be limited	WII affect MBSE project			Software cost and liscence	1	Using carried student version Budget limit	months and	1	10	action required	max	110/21	Have proper tawn mover requirments and parameters						,,,,,
3	Repeatable and moldable	The model needs to repeat function ability each time a parameter is changed. The contents of the	MBSE carreo	9	3	Having Inaccurate parameters	1	Cameo Testing	Have proper lawn mover requirment is and	1	1	action required	kaber a	11021	Have proper lawn mover requirments and parameters	11/3/21	9	1	1		0.0%
4	Provide instant	The model needs to	Wil affect	1	5	Having	1	Provide	Provide	1	1		sydne	11021	Have proper	11/3/21		1	1	1	



6. Motor Parametric

Concepts



Concept:

Breakdown of a DeWaltlawn mower

- Include all the systems

& interconnections

- Ability to input requirements & get different outputs based on the performance of the mower

Testing

Motor Testing Table

٦	Resistance (Ohms)	Test Voltage (Volts)	Result Current	Pass/Fail
			(Amps)	
	360	40	9	Fail
	360	41	8.78	Fail
ſ	360	42	8.57	Fail
	360	43	8.37	Fail
	360	45	8	Fail
ĺ	360	50	7.2	Fail
	360	37	9.7	Fail
	360	38	9.47	Fail
Ī	360	39	9.2	Pass

Controller Testing

Resistance (Ohms)	Test Current (Amps)	Result Blade Speed	Pass/Fail			
		(RPM)				
360	8.6	3096	Pass			
360	8	2880	Pass			
360	8.3	2988	Pass			
360	8.9	3204	Pass			
360	9	3240	Pass			
360	9.1	3276	Pass			
360	9.2	3312	Pass			
360	9.25	3330	Pass			
360	9.3	3348	Pass			
360	8.8	3168	Pass			